

Communication, corporate governance, and organizational structure

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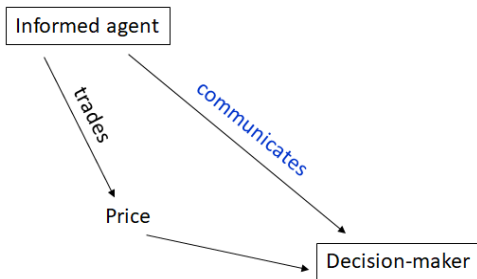
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How dispersed information affects decisions

- Information is typically dispersed
 - Decision-makers are not perfectly informed
 - Other agents often know additional information
- How does this information affect decisions?



Motivation

Decision-makers often get advice from informed but biased agents

- Top executive and divisional manager
- Financial advisor advising a client on portfolio allocation
- VC and entrepreneur
- Investment banker advising a buyer or seller in M&A
- Board and CEO
- Managers and proxy advisors advising shareholders on voting
- Shareholders advising management: activists, advisory votes

Questions

- How much information can be communicated?
- How to design decision-making processes to maximize efficiency?
- How does private, unobserved communication explain observed phenomena?

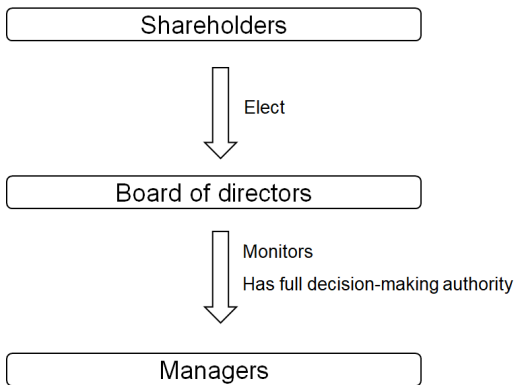
Outline

1. **Cheap talk communication**
 - **Crawford and Sobel 1982**
2. Allocation of control rights
 - Dessein 2002
3. Corporate finance and governance applications
4. Dynamic communication
 - Grenadier, Malenko, Malenko 2016

Strategic information transmission

- When a biased agent communicates his information to the decision-maker, he has incentives to “misreport”
 - to tilt the decision-maker towards his preferred decision
- This makes communication less effective
- Questions
 - How much information can be communicated?
 - How efficient are decisions?

Example: Board and CEO



Crawford and Sobel 1982: Setup

Two players

- Sender
 - has private information θ and communicates it
 - e.g., CEO knows information about project payoff
- Receiver
 - takes action a
 - e.g., board decides how much to invest in a project

Setup: Timeline

1. S privately observes state θ
 - $\theta \sim F(\cdot)$, $f(\cdot)$ on $[\underline{\theta}, \bar{\theta}] = [0, 1]$
 - We will focus on **uniform** distribution (and **quadratic** preferences), but the paper is more general
 - other common distribution: binary
2. S sends message $m \in M$ to R
 - information is **non-verifiable**, so S can misreport
3. R chooses action $a \in \mathbb{R}$

Setup: Payoffs

$$U^R(a, \theta) = -(a - \theta)^2$$
$$U^S(a, \theta, b) = -(a - (\theta + b))^2$$

- Receiver's optimal action is θ
- Sender's optimal action is $\theta + b$
 - E.g., $b > 0$ from empire-building
 - Note: S still cares about fundamentals. Otherwise, no communication at all is possible.

Talk is “cheap”: message m does not affect S's payoff

- unlike in costly signaling games (e.g., Spence on education)
 - signaling is costly but credible
 - cheap talk communication is costless but less credible

Bayes-Nash equilibrium

- Sender's message strategy $m : [\underline{\theta}, \bar{\theta}] \rightarrow M$ and
- Receiver's action strategy $a : M \rightarrow \mathbb{R}$ such tha

$$m(\theta) \in \max_m U^S(a(m), \theta, b) \quad (1)$$

$$a(m) \in \arg \max_a \mathbb{E}[U^R(a, \theta) | m] = \mathbb{E}[\theta | m] \quad (2)$$

$$= \arg \max_a \int_{\underline{\theta}}^{\bar{\theta}} U^R(a, \theta) p(\theta | m),$$

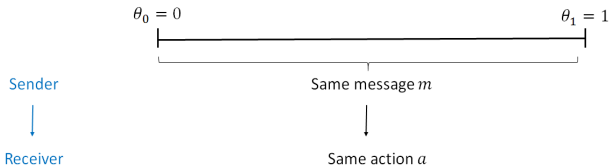
where $p(\theta | m)$ are beliefs given Bayes rule

- if $q(m|\theta)$ is prob. of m given θ , $p(\theta|m) = \frac{q(m|\theta)f(\theta)}{\int q(m|\theta)f(\theta)d\theta}$

Equilibria

1. Uninformative (“babbling”) equilibrium always exists

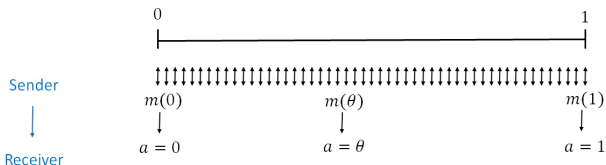
- E.g., S always sends the same message
 - many other ways to construct eqm, e.g., random messages
- R ignores messages and takes action $\mathbb{E}[\theta]$
 - given this, S is indifferent \Rightarrow optimal to “babble”



Equilibria

2. Fully informative equilibrium exists only if $b = 0$

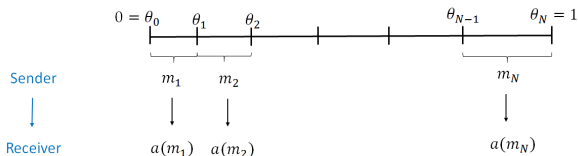
- In such eqm, $m(\theta_1) \neq m(\theta_2)$, so R knows state for sure
 \Rightarrow Given $m(\theta)$, R takes $a = \theta$
- But then, S wants to send $\tilde{m} = m(\theta + b)$



Structure of informative equilibria

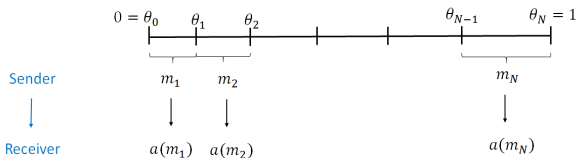
3. Informative equilibria have a “partition” structure

- Points $0 = \theta_0 < \theta_1 < \dots < \theta_{N-1} < \theta_N = 1$
- All S types in $[\theta_{i-1}, \theta_i]$ send the same message
 - and hence induce the same action of R



Structure of informative equilibria

- Intuition: Close types must send the same message
 - otherwise low type would mimic high type to induce a higher a
- Types at cutoff points are indifferent
 - ⇒ types just to the left don't mimic types just to the right



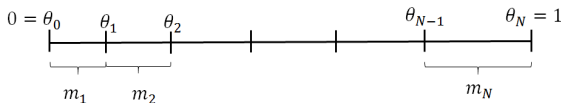
Characterizing partition equilibria

1. Optimality for R:

$$a_i = \mathbb{E} [\theta | m_i] = \frac{\theta_{i-1} + \theta_i}{2}$$

2. Optimality for S (indifference of cutoff types):

$$(a_i - (\theta_i + b))^2 = (a_{i+1} - (\theta_i + b))^2$$



Characterizing partition equilibria

1. Optimality for R:

$$a_i = \mathbb{E}[\theta | m_i] = \frac{\theta_{i-1} + \theta_i}{2}$$

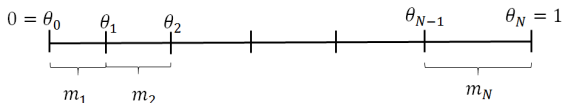
2. Optimality for S (indifference of cutoff types):

$$(a_i - (\theta_i + b))^2 = (a_{i+1} - (\theta_i + b))^2$$

$$\Rightarrow \theta_{i+1} - \theta_i = \theta_i - \theta_{i-1} + 4b$$

Partition size is increasingly large (by 4b)

$$\theta_{i+1} - \theta_i = \theta_i - \theta_{i-1} + 4b$$



- “Larger” messages are more noisy \Rightarrow exaggeration is costly \Rightarrow S is induced to tell the truth
 - Larger bias $b \Rightarrow$ stronger incentive to exaggerate \Rightarrow larger increase in partition size
- “Common sense” interpretation:
 - If a person who prefers large projects recommends a “large” project, his message is not very informative
 - If he recommends a “small” project, this is more revealing

Characterizing partition equilibria

$$\theta_{i+1} - \theta_i = \theta_i - \theta_{i-1} + 4b$$

- Second-order difference equation \Rightarrow using $\theta_0 = 0$, solution is

$$\theta_i = \theta_1 i + 2i(i-1)b$$

- Using $\theta_N = 1$ for a given N , we get unknown θ_1
- There are multiple equilibria with different N , as long as $2N(N-1)b < 1 \Leftrightarrow N \leq N_{\max}$

Selecting among equilibria

- There are multiple equilibria with different N for $N \leq N_{\max}$
 - $N = 1$ gives the uninformative one
 - $N = N_{\max}$ gives the **most informative** one

- Ex-ante expected utilities

$$EU^R = -\sigma^2$$

$$EU^S = -(\sigma^2 + b^2)$$

where σ^2 is residual variance; $\sigma^2 \searrow N$ for $N \leq N_{\max}$

- S would be better off if he could commit not to lie, but cannot
- The most informative equilibrium **Pareto-dominates** all others \Rightarrow typically selected

Properties of the most informative equilibrium

$$2N(N-1)b < 1 \Leftrightarrow N \leq N_{\max} = \left\langle -\frac{1}{2} + \frac{1}{2}\sqrt{1 + \frac{2}{b}} \right\rangle$$

where $\langle x \rangle$ is the smallest integer greater than or equal to x

- **More aligned preferences \Rightarrow more informative communication**
 - As $b \searrow$, N_{\max} and expected utility of R and S \nearrow
 - If $b \rightarrow 0$, $N_{\max} \rightarrow \infty$: full communication
 - If $b \geq \bar{b}$ ($= \frac{1}{4}$), $N_{\max} = 1$: only babbling equilibrium
- Source of inefficiency is **information loss**
 - not bias directly, because R is the **decision-maker** and “de-biases” messages

Other models of strategic communication

1. Cheap talk: **non-verifiable** information
 2. Voluntary disclosure of **verifiable** information
 - S can stay silent but cannot misreport
 - Grossman 1981; Milgrom 1981; Verrecchia 1983; Dye 1985
 3. Bayesian persuasion
 - S **commits** to a mapping from states to R's signals
 - i.e., info is also verifiable, but S “designs” its distribution
 - Kamenica-Gentzkow 2011
- Different results; different applications

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Allocation of control rights

- If uninformed **principal has control** over decisions:
 - decisions are unbiased
 - but agent's information is partly lost
- What if **principal delegates control** to the agent?
 - decisions are biased
 - but agent's information is not lost
- **What is the optimal allocation of control rights?**

Applications

- Top executive and divisional manager
- Board and CEO
- VC and entrepreneur
- Financial advisor advising a client on portfolio allocation

Allocation of control: Dessein (2002)

- Consider the Crawford-Sobel (1982) setup
 - We will focus on the uniform-quadratic setup
 - Dessein's setup is more general
 - **Principal** = Receiver; **Agent** = Sender
- **When does P prefer to delegate authority to A?**

Keeping authority vs. Delegating

P keeps authority

- Partial communication with $N(b) = N_{\max}$ partitions
- P chooses $\frac{\theta_i + \theta_{i-1}}{2}$ - unbiased, but not fully informed
- P's expected utility = - residual variance, or

$$\mathbb{E}_{keep}[U^P] = -\frac{1}{12N(b)^2} - \frac{1}{3}b^2 (N(b)^2 - 1)$$

P delegates authority to A

- A chooses $a_A = \theta + b$ - informed but biased
- P's expected utility is $-\mathbb{E}(a_A - \theta)^2$:

$$\mathbb{E}_{delegate}[U^P] = -b^2$$

Key takeaways

Trade-off:

Delegate \Rightarrow loss of control (biased decision)

vs.

Keep authority \Rightarrow loss of information (less informed but unbiased decision)

Key takeaways (cont.)

- **As bias b increases, P is worse off in both regimes**
 - Communication is worse, so $\mathbb{E}_{keep}[U^P]$ decreases
 - A's decisions are more biased, so $\mathbb{E}_{delegate}[U^P]$ also decreases
- **When bias b is large, delegation is inferior**
 - P's loss from delegation is unlimited
 - P's loss from keeping authority is limited: the worst is an uninformed decision based on priors

Comparison for small biases

- When bias is large, delegation is inferior
- As bias decreases, both regimes give P higher payoff
- Which dominates when bias b is small?

- Dessein's result: **Delegation is superior when b is small**
 - uniform-quadratic setup:
 - delegation \Rightarrow P's loss is second-order in b
 - communication \Rightarrow P's loss is first-order in b
 - shows this also holds for some more general setups

Predictions

- Dessein's predictions: Delegation is more likely when
 1. Agent's information advantage is large relative to his bias
 2. Principal is more risk-averse
 - unbiased actions with large variance under P's authority
- Large theoretical literature, but scarce empirical evidence
 - Organizational economics: determinants of decentralization
 - Acemoglu et al. 2007; Bloom et al. 2014; Huang et al. 2017; Dessein et al. 2018
 - Finance settings: VC contracts, board control

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Some finance applications

- **Financial markets**

- Benabou-Laroque 1992: informed agent 1) manipulates prices through public messages, 2) trades before or after

- **Financial analysts**

- Ottaviani-Sorensen 2006: unbiased sender, cares about his reputation for ability

- **Mergers and acquisitions; auctions**

- Levit 2017: board advises target shareholders whether to accept a takeover offer
- Quint-Hendriks 2018: nonbinding bids prior to binding
- Malenko-Tsoy 2019: auction design when bidders learn their private valuations from biased advisors (investment bank/CEO)

- **Corporate governance**

- board-CEO relationships; shareholder activism; voting

Application of Dessein 2002 to board-CEO

- Board = Principal
 - by law, has full decision-making authority
- CEO = Agent
 - better informed but biased
- **Implication:** Board should delegate decisions for which CEO's information is large relative to his bias
- Does the board have commitment power to delegate?
 - e.g., irreversible or very costly to reverse decisions
 - across decisions: through weaker governance
 - dual class shares; less independent board; CEO-chairman

What is unique to board-CEO relationships?

1. Advisory role is important

- industry executives, finance experts, lawyers, academics
- Hence P is also informed
 - two-sided private information
 - Adams-Ferreira 2007; Chakraborty-Yilmaz 2017; Harris-Raviv 2005, 2008, 2010; Kakhbod-Loginova-Malenko-Malenko 2019

2. Dual advisory and monitoring roles

- Board advises CEO, but also interferes with his decisions
- How do the two roles interact?
 - Adams-Ferreira 2007; Levit 2018

Harris-Raviv 2008: Two-sided private information

- Outside directors and Manager/insiders

$$U_O = - (a - \theta)^2$$

$$U_M = - (a - (\theta + b))^2$$

and

$$\theta = \theta_O + \theta_M$$

where $\theta_O \sim U[0, A_O]$ and $\theta_M \sim U[0, A_M]$ are independent

- A_O, A_M measure importance of each player's information
-
- Outsider control vs. Manager control
 - party with control gets advice from party without control

Two-sided private information

- Outsider control: O's action after getting message m is

$$a_O^* = \theta_O + \mathbb{E}[\theta_M | m]$$

- But then for M:

$$a_O^* - (\theta + b) = \mathbb{E}[\theta_M | m] - \theta_M - b$$

which is the same as without O's private information

- M can perfectly predict the effect of his messages on his utility
 - hence we can solve the standard Crawford-Sobel setup
-
- Generally: similar trade-off between info loss and biased decisions
 - delegation is more likely when Manager's info is important relative to his bias and Outsiders' info
 - e.g., dual class shares in high-tech firms

Private information of the board

- Main difference due to two-sided private information:
 - Outsiders can use their info to decide whether to delegate
 - i.e., allocation of control becomes state-contingent
- **Result:** If $b > 0$, outsiders delegate control to M iff $\theta_O > \bar{\theta}$
 - i.e., delegation is more likely when O's private information is consistent with M's bias
 - Reason: when O communicate to M, partitions are smaller when θ_O is large \Rightarrow less information is lost for large $\theta_O \Rightarrow$ loss from delegation is lower

Private information of the board

- Harris-Raviv 2005, 2008, 2010: take conflict of interest b as given
 - Ask: Given b , should board delegate decisions?
- Adams-Ferreira 2007; Chakraborty-Yilmaz 2017; Malenko 2014:
 - Ask: What is the optimal board composition, i.e., b ?
- Key takeaway: **Less independent boards can be optimal**
 - to improve communication between boards and managers
 - to use managers' information better

Dual advisory and monitoring role

- Adams-Ferreira (JF 2007); Levit (JF forthcoming):
 - Advising = communicating to M, with M choosing a
 - Monitoring = affecting a , fully or partially

Conclusions: **These two roles conflict**, for two very different reasons:

- Adams-Ferreira: Board's info relies on M giving info to the board
 - M will not give info because of monitoring
 - Implications: friendly boards; two-tier boards
- Levit: advising \rightarrow M takes action \rightarrow costly intervention by board
 - Communication is less informative if intervention is possible

Levit (2018): Setup

Timing

1. P observes $\theta \sim U [\underline{\theta}, \bar{\theta}]$ and sends message m
2. A chooses project size $a \in \mathbb{R}$
3. P decides how much to **intervene**, Δ at cost $\delta C(\Delta)$
 - final project size is $a - \Delta$

We will focus on quadratic preferences and cost $\delta\Delta^2$

- $U_P = -(a - \theta)^2$, $U_A = -(a - (\theta + b))^2$
- but results are more general

Analysis: Intervention stage

- After A chooses a , P chooses Δ to maximize

$$-(a - \Delta - \theta)^2 - \delta\Delta^2$$

\Rightarrow P chooses $\Delta^* = \frac{a-\theta}{1+\delta}$

- if $\delta > 0$, P does not fully “undo” the agent’s bias

Analysis: Communication stage

Anticipating $\Delta^*(a) = \frac{a-\theta}{1+\delta}$, at the communication stage:

- P maximizes

$$-(a - \Delta^* - \theta)^2 - \delta \Delta^{*2}$$

- P's ideal action is $a_P = \theta$
 - maximizes his utility from the action
 - minimizes his costs of intervention

Analysis: Communication stage

Anticipating $\Delta^*(a) = \frac{a-\theta}{1+\delta}$, at the communication stage:

- A maximizes

$$-(a - \Delta^* - (\theta + b))^2$$

- A's ideal action satisfies $a_A = \theta + b + \Delta^*(a_A) \Rightarrow$

$$a_A = (\theta + b) + \frac{b}{\delta}$$

- A's ideal action "overshoots" relative to the action that is eventually implemented

Analysis: Communication stage

- P's ideal action is θ
- A's ideal action is $(\theta + b) + \frac{b}{\delta}$
- Since “effective” bias exceeds b , communication is worse
 - this negative effect is strongest when δ is small or b is large
- Intuition:
 - A expects intervention \Rightarrow deliberately “overshoots” as if his bias is larger \Rightarrow P has even stronger incentives to understate fundamentals
- This negative effect of intervention can dominate
 - P can be better off without the power to intervene

Other governance applications

Shareholder activism

- Levit (JF forthcoming)
- Levit (RFS 2019): effect of public campaigns and exit on communication

Shareholder voting

- Voting on many issues is non-binding and hence, effectively, is similar to communication
 - Levit-Malenko (JF 2011), Kakhbod-Loginova-Malenko-Malenko (2019): multiple senders
- Proxy advisors' recommendations to shareholders
 - Levit-Tsoy (2019): multiple receivers & uncertainty about S's bias
 - Ma-Xiong (2019): Bayesian persuasion

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- **Grenadier, Malenko, Malenko 2016**
- Bizzotto et al 2018; Ely 2017; Ely-Szydlowski 2017; Orlov et al 2018

Role of commitment

We have assumed **limited commitment** by the Principal

- Dessen: **P can commit not to overrule A** when giving authority
- But **P cannot commit how he reacts to A's messages**
 - otherwise would be better off
- Contracts are incomplete, hence allocation of authority matters

Limited commitment by Principal

- P cannot commit how he reacts to A's messages
 - action $a(m)$ is *ex-post optimal* for P
- Otherwise, mechanism design approach and revelation principle
 - P commits to actions as a function of A's messages; all information is truthfully reported
 - Optimal mechanism can be implemented via *constrained delegation*: A picks from a restricted "delegation set"
 - Dessein 2002: unconstrained delegation
 - E.g. Holmström 1984; Melumad-Shibano 1991; Alonso-Matouschek 2008; Amador-Bagwell 2013
- As we will see, time can indirectly give P this commitment power

Grenadier, Malenko, Malenko (2016)

Motivation

- Most decisions are not purely static:
 - many decisions are about **timing**: bringing a new product, shutting down a plant, drilling an oil well
 - most decisions can be delayed

Questions

- How do firms make timing decisions?
 - How does information flow from lower to upper levels?
 - What decisions should be delegated?

Preview of results

Timing decisions have different economics from static decisions:

- Asymmetry between “delay bias” and “early exercise bias”
 - E.g., shutting down a plant vs. product launch
 - Reason: Irreversibility of time
- Delay bias:
 1. Often full communication of information, but too late
 2. Irreversibility of time gives commitment power
 3. Delegation never helps
- Early exercise bias:
 1. Noisy communication
 2. Delegation helps if the bias is low

Simple example

- P decides on **timing** t of taking an action
 - time moves continuously from 0; no discounting
 - general setting: call option exercise
- Optimal timing depends on parameter $\theta \sim U[1, 2]$

$$U^P(t, \theta) = -(t - \theta)^2$$
$$U^A(t, \theta, b) = -(t - (\theta + b))^2$$

P's optimal timing: θ

A's optimal timing: $\theta + b$

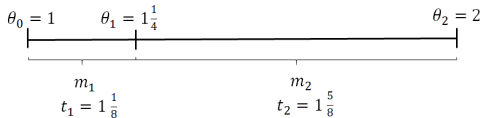
- $b < 0$: bias towards earlier exercise (e.g., product launch)
- $b > 0$: bias towards later exercise (e.g., plant closure)

Comparing static and dynamic communication

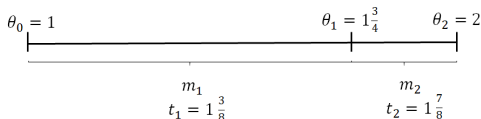
1. **Static:** A only communicates to P at $t = 0$
 - identical to Crawford-Sobel
 - **direction of the bias does not matter**
2. **Dynamic:** A communicates to P continuously
 - **direction of the bias is crucial**

Static communication

- A sends a single message at $t = 0$; P decides when to exercise
- Most informative equilibrium:
 1. $b = \frac{1}{8}$ (late exercise bias)



2. $b = -\frac{1}{8}$ (early exercise bias)



Dynamic communication: Timing

Heuristic timing of events over $[t, t + dt]$:

1. A decides on message m_t to send to P
2. P decides whether to exercise or not
 - If P exercises, the game ends, and players receive payoffs
 - Otherwise, the game continues

Dynamic communication: Late exercise bias

Consider **late exercise bias**: $b = \frac{1}{8} > 0$

- A's optimal timing is $t_A^* = \theta + b$

Cutoff equilibrium:

- A sends message $m = 0$ ("wait") while $t < t_A^*$
and message $m = 1$ ("exercise") once $t \geq t_A^*$
- P **follows recommendation** until $\tau^* = 2 - b$
 - if gets $m = 0$ ("wait"), waits
 - if gets $m = 1$ ("exercise"), exercises
- P exercises at $\tau^* = 2 - b$ if A still recommends to wait

Late exercise bias: Why is this equilibrium?

P: After getting the message to “exercise”

- If P gets the first message to “exercise” at t , infers $\theta = t - b$
- But his optimal timing to exercise has already passed
⇒ finds it optimal to exercise
- Ideally, would have “gone back in time” and exercised at $t - b$, but cannot
- P cannot “de-bias” A’s messages ⇒ follows them
 - In a static problem, “de-biasing” always occurs

Late exercise bias: Why is this equilibrium?

P: Before getting the message to “exercise”

- P trades off waiting for information vs. delay
- At time t , P knows that $t < \theta + b \Leftrightarrow \theta > t - b$
- At first, it is optimal to wait, to get more info from A
- But as time goes by, value of waiting for A's info declines
 - So at some point, P exercises

Late exercise bias: Why is this equilibrium?

P: Before getting the message to “exercise”

- P knows that $\theta > t - b$
- Strategy: P waits until τ and then exercises
 - $\theta < \tau - b$: A will recommend to exercise at $\theta + b < \tau$, resulting in P's loss of b^2
 - $\theta > \tau - b$: P will exercise at τ , resulting in P's loss of $(\tau - \theta)^2$

$$\begin{aligned}\tau^* &= \arg \min_{\tau} \frac{1}{2 - (t - b)} \left(\int_{t-b}^{\tau-b} b^2 d\theta + \int_{\tau-b}^2 (\tau - \theta)^2 d\theta \right) \\ &= 2 - b\end{aligned}$$

Late exercise bias: Why is this equilibrium?

A: Why it is optimal to recommend exercise at $t_A^* = \theta + b$

- If $\theta < \tau^* - b$, gets his most preferred timing
 - information is fully revealed for these types
 - but timing is delayed relative to P's optimum
- If $\theta > \tau^* - b$, would like to delay beyond τ^* , but cannot benefit from deviating since P does not delay beyond τ^*

Dynamic communication: Early exercise bias

Consider **early exercise bias**: $b = -\frac{1}{8}$

- A's optimal timing is $t_A^* = \theta - \frac{1}{8}$

A similar equilibrium does not exist:

- Suppose A recommends to “wait” until t_A^* , and recommends to “exercise” at t_A^*
- If P gets the first message to “exercise” at t , infers $\theta = t + \frac{1}{8}$
- Then P optimally exercises at $t + \frac{1}{8}$
- But then A has incentives to recommend earlier exercise

In a general setting, show that all equilibria have a partition structure

Takeaways

- With a late exercise bias, P follows A's recommendations
 - time gives P commitment power not to overrule A
 - commitment power makes communication efficient
- With an early exercise bias, time does not give commitment
- Implications for optimal allocation of control
 - Delegation is less valuable under late exercise bias
 - Direction of the bias is crucial for optimal allocation of control

Implications for allocation of control

Grenadier-Malenko-Malenko (2016) show in a more general setup:

1. Communication equilibrium **implements the optimal mechanism** with commitment when A is biased towards **late** exercise
 - but not when A is biased towards early exercise
2. Hence, **delegation is never superior** to centralization under **late** exercise bias
 - Decisions like plant closures should never be delegated
3. But delegation is optimal if bias is small under **early** exercise bias
 - Decisions like product launches should be delegated if the agent's bias is small enough

Conclusions

- Relevant information is often dispersed. Decision-makers get advice from informed but biased parties.
- Conflicts of interest limit effective communication and thus hinder efficiency.
- Allocation of control crucially affects how informative and unbiased decisions are.